

Analog modulations Communication Theory

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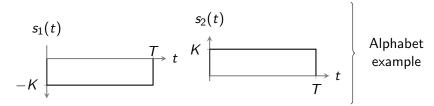
Introduction

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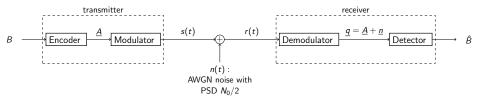
Angular modulations

Analog vs digital communications systems

In digital systems, information is carried by symbols in an alphabet,

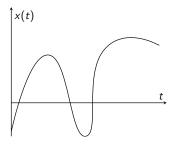


and the most basic scheme of a system is...



Analog vs digital communications systems

In analog systems, information is contained in a continuous waveform...



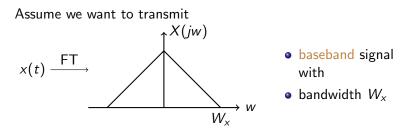
- 2 possibilities:
 - discretize the signal and transmit it using a digital system
 - transmit it directly using an analog system.

We focus on the latter approach...2 types of channels:

- Baseband
- Passband

Angular modulations

Transmission of a baseband signal



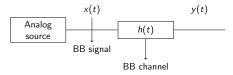
...and we model the channel as a Linear Time Invariant system...

$$\begin{array}{c|c} x(t) \\ \hline X(jw) \end{array} \begin{array}{c} h(t) \\ H(jw) \end{array} \begin{array}{c} y(t) = x(t) * h(t) \\ Y(jw) = X(jw)H(jw) \end{array}$$

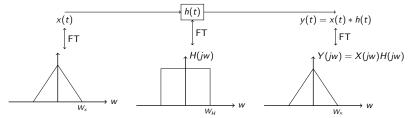
Angular modulations

Baseband transmission

The information signal is transmitted as is



Assuming an ideal baseband channel whose bandwidth is larger than that of the signal $(W_H > W_x)...$

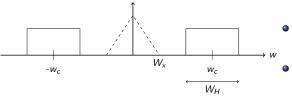


Examples: telephone subscriber loop, public address systems, closed-circuit TV

Passband transmission

Let us consider an ideal passband channel whose

- I bandwidth is larger than that of the signal, and whose
- enter frequency, w_c, is much larger than the bandwidth of the signal.



- passband channel with
- bandwidth W_H

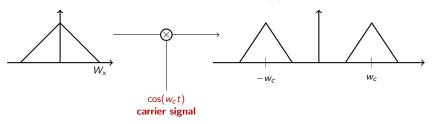
2 entails $w_c - \frac{W_H}{2} > W_x$, and hence

$$Y(jw) = X(jw)H(jw) = 0,$$

i.e., the signal cannot get through.

Modulation

This is solved by shifting the spectrum of x(t)...



Mathematically,

$$X(t)\cos(w_c t) \xleftarrow{FT} rac{1}{2}X(j(w-w_c)) + rac{1}{2}X(j(w+w_c))$$

This operation is called modulation. It involves three signals

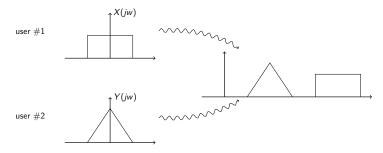
$$\underbrace{y(t)}_{\substack{\text{modulated}\\ \text{signal}}} = \underbrace{x(t)}_{\substack{\text{modulating}}} \cdot \underbrace{\cos(\omega_c t)}_{\substack{\text{carrier}\\ \text{signal}}}$$

Angular modulations

Modulation

Other uses:

• multiuser systems



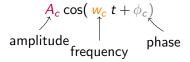
- protection against
 - noise
 - unauthorized users listening in the channel

Types of modulation

Let us consider an information signal, x(t), that is

- a baseband signal, i.e., $X(jw) = 0, \forall |w| > W$
 - a realization of a band-limited WSS random process X(t) with $S_X(jw) = 0, \forall |w| > W$
- a power signal, i.e., whose power is finite

Transmission of x(t) is achieved by embedding it in a carrier signal of the form



and x(t) can be modulating

- the amplitude,
- the frequency, or
- the phase.

Linear vs. angular modulations

In general, the modulated signal has the form

$$y(t) = r(t)\cos(w_c t + \varphi(t))$$

• x(t) is embedded in $r(t) \rightarrow \text{linear}$ or amplitude modulation¹

$$y(t) = r(t)\cos(w_c t + \varphi)$$

with constant frequency and phase.

• x(t) is embedded in $\varphi(t) \longrightarrow$ angular modulation

$$y(t) = A\cos(w_c t + \varphi(t))$$

with constant amplitude and frequency.

 $^{1} \not\Rightarrow r(t) = x(t)$...since some transformation might be applied

$$y(t) = r(t)\cos(w_{c}t + \varphi) = r(t)(\cos(w_{c}t)\cos\varphi - \sin(w_{c}t)\sin\varphi)$$

=
$$\underbrace{r(t)\cos\varphi}_{\substack{x_{i}(t)\\\text{in-phase com-}\\\text{ponent}}} \cos(w_{c}t) - \underbrace{r(t)\sin\varphi}_{\substack{x_{q}(t)\\\text{quadrature}\\\text{component}}} \sin(w_{c}t),$$

 $x_i(t)$ and $x_q(t)$ are rewritten in a more convenient form

•
$$x_i(t) = r(t) \cos \varphi = A_c + A_m x(t)$$

• $x_a(t) = r(t) \sin \varphi = A_n \tilde{x}(t)$

where $\tilde{x}(t)$ is a transformation of x(t). The new parameters determine the type of modulation:

- $A_c \neq 0$, $A_m \neq 0$, $A_n = 0 \rightarrow AM$ modulation (conventional amplitude modulation)
- $A_c = 0, A_m \neq 0, A_n = 0 \rightarrow \text{DSB}$ modulation (Double Side Band modulation)
- $A_c = 0, A_m \neq 0, A_n \neq 0 \rightarrow SSB$ modulation (Single Side Band modulation)

AM modulation

$$y(t) = (A_{c} + A_{m}x(t))\cos(w_{c}t)$$

Let us assume $|x(t)| \le 1$ (if not, we can do $x_{n}(t) = \frac{x(t)}{\max |x(t)|}$,)
$$\int_{0.5}^{0} \frac{1}{0} \frac{$$

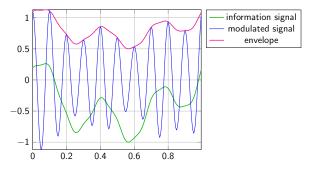
with

$$m = \frac{A_m}{A_c} \equiv$$
modulation index

Angular modulations

AM demodulation

 $A_c(1 + mx(t)) \ge 0$ implies this signal matches the envelope of the modulated signal, y(t)



8 Envelope of a signal

The **envelope** of an oscillating signal (for example, a cosine) is a *smooth* signal that outlines its extremes.

Angular modulations

AM demodulation

In order to guarantee $A_c(1 + mx(t)) \ge 0$, and assuming $|x(t)| \le 1$ (i.e. it is *normalized*), it is enough to choose

 $0 < m \le 1$.

Indeed,

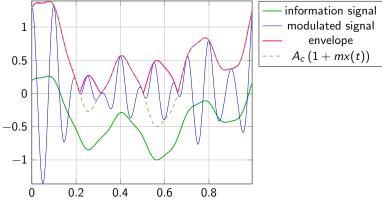
$$egin{array}{l} 0 < m \leq 1 \ |x(t)| \leq 1 \end{array}
ight\} \Rightarrow (1 + mx(t)) \geq 0 \Rightarrow {\sf demodulation} {
m ~is~very~easy}$$

extract envelope solve for
$$x(t)$$

 $y(t) \xrightarrow{\uparrow} A_c(1 + mx(t)) \xrightarrow{\uparrow} x(t)$

Overmodulation

If m > 1, it might happen that $A_c(1 + mx(t)) < 0$ at some point...



The envelope is **not** $A_c(1 + mx(t))$ anymore, and hence demodulation is not so easy. It is called **overmodulation**.

Angular modulations

Angular modulations

The information is in the argument of the carrier

Drawbacks

- they are way **more complex** than linear modulations
 - sometimes, they need to be studied through approximations
- they take up more bandwidth

Advantages

- they are less affected by noise...
 - they trade off bandwidth for immunity against noise

Angular modulations

Algebra for Angular modulations

$$y(t) = A\cos(w_c t + \varphi(t)) = A\cos\phi(t),$$

where

$$\phi(t) = w_c t + \varphi(t) \equiv \textit{instantaneous}$$
 phase

From it, we have

$$rac{d\phi(t)}{dt} = w_i(t) rac{ ext{rad}}{ ext{second}} \equiv ext{instantaneous frequency},$$

in radians, which becomes

$$rac{1}{2\pi}rac{d\phi(t)}{dt}=f_i(t)\,\mathsf{Hz}\equiv \textit{instantaneous frequency}.$$

in hertz.

Doing some algebra

$$f_i(t) = \frac{1}{2\pi} \frac{d\phi(t)}{dt} = \frac{1}{2\pi} \frac{d\left(w_c t + \varphi(t)\right)}{dt} \stackrel{w_c = 2\pi f_c}{=} f_c + \frac{1}{2\pi} \frac{d\varphi(t)}{dt}$$

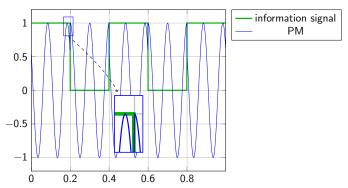
Phase modulation

Being x(t) the information signal...

 $\varphi(t) = \beta x(t) \longrightarrow$ Phase modulation (PM)

with $\beta \equiv$ phase deviation constant. Hence,

 $y(t) = A\cos(w_c t + \beta x(t))$



Angular modulations

Frequency modulation

 $f_i(t) = f_c + f_d x(t) \longrightarrow$ Frequency modulation (FM)

with $f_d \equiv$ frequency deviation. It can be proved that

$$\varphi(t)=2\pi f_d\int_{-\infty}^t x(u)du,$$

and hence

$$y(t) = A\cos\left(w_c t + 2\pi f_d \int_{-\infty}^t x(u) du\right)$$

